# Quick Setup Guide for IntelliAg Model YP24 15”

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The Quick Setup Guide assumes the Virtual Terminal, Master Switch, Working Set Master Module, Working Set Member Module, and all sensors have been connected and properly installed. Reference Operator’s manual for installation instructions. **NOTE: The master switch is only required for hydraulic control systems. Reference the manual for instructions to assign a master switch as an auxiliary input.**

## STEP 1: Pre-Programming Preparation:

1. Power on vehicle via ignition switch to activate Virtual Terminal (VT). Main menu will display pre-programmed default settings.
2. If errors are detected (e.g., failed sensors, incorrect configuration) an alarm and code displays. Alarms are silenced by pressing the Alarm Cancel button . Refer to Operator’s manual for troubleshooting assistance.
3. The system has three user levels. The system loads in User Level 1 (operator level) at every power cycle. Access to User Level 2 and 3 screens to setup constants (system configuration) requires a password.

## STEP 2: Change User Level to Dealer Level

**To change the user level, a 6-digit password is required. Password includes the five-digit serial number found on the label of the Working Set Master or Information screen.**

1. On the IntelliAg Main Work screen, press the Diagnostics button .
2. At the Diagnostics screen, press the Information button .
3. At the Information screen, record serial number of WSMT.
4. Press the Password button .
5. On the Password screen, enter the 6 digit password as follows: enter the first digit as 2 for User Level 2. For the next five digits, enter the Working Set Master serial number taken from the WSMT or Information screen.
6. Press the OK button . “Dealer screens on” appears at the bottom of screen confirming the password and dealer screens are activated.
7. Press the Work Screen button to return to the Main Work screen.

## STEP 3: Auto Configuration (Identifies sensors connected to each module)

**Auto config is performed at the factory, but may need to be done in the field as changes are made to the system or if options are added to the base planter.**

1. Verify Auto Config results are correct. Check that the correct number of rows are assigned to the correct module and number of hopper sensors are assigned accurately.

**To Run Auto Config:**

1. Press the Next Page button until the Module Configuration button appears.
2. Press the Module Configuration button .
3. Press the AUTO CONFIG button .
4. Hour glass will indicate system is being configured detecting the presence of seed or hopper sensors connected to each module and will be automatically assigned to the appropriate module.
5. When Auto Config completes, press the Row Assign button to display the Row Assignment screen to verify correct Row # is assigned to the correct module based on serial number.
6. Enter # of rows assigned to each module.

Module Configuration Screen

| | | SERIAL NUMBER | MODULE TYPE | MODULE ADDR. |
|---|---|---|---|---|
| (optional) | ✔ | 10001 | WSMB-POM | 1 |
| | ✔ | 10002 | WSMB-POM | 2 |
| | ✔ | 10001 | WSMB-18R | 3 |
| | ✔ | 10001 | WSMT-GY | 4 |
| | ✔ | 10002 | WSMB-18R | 5 |
| (optional) | ✔ | 10003 | WSMB-POM | 6 |
| | ✔ | 10001 | WSMB-CFM | 7 |

Seed Sensor Configuration Screen

| MODULE ADDR. | MODULE TYPE | # OF ROWS | ROW #’s |
|---|---|---|---|
| 1 | WSMB-18R | 18 | 1- 18 |
| 2 | WSMT-GY | 11 | 19-29 |
| 3 | WSMB-Rows | 18 | 30-47 |
| | | | |
| | | | |
| | | | |
| | | | |

## STEP 4: Row Status/Row Width Setup

1. At the Row Assignment screen, press the Row I/O button .
2. Begin entering desired values using **Table A** as reference.
3. Press the Work Screen button when Row Status/Row Width configurations are complete to return to the Main Work screen.

## STEP 5: Material Configuration Setup (Controlled Hydraulic Drive)

*16 different materials can be configured for use as planter controls. Reference the System Configuration section in the Operator’s manual for additional information.*

1. At the Main Menu screen, press the Control Setup button .
2. Select and press one of the Material buttons (Material 1-16).
3. Enter desired values from **Table B**.
4. Press the Control Setup button to return to the Control Setup screen.
5. Repeat steps 2-4 for additional materials.
6. Press the Channel Setup button to proceed to channel setup screen.

| TABLE A: Row Status/Row Width Setup | Default Value or Value to Enter | Instructions/Definitions |
|---|---|---|
| Row Width | 15” | Enter row width distance in inches to calculate seed rate correctly. NOTE: Using 15” planter in 30” mode should change On/Off pattern to Every 2nd Row Off. |
| Auto Update Width | Enabled | When enabled, implement width will automatically calculate. If disabled, manually enter implement width. |
| On/Off Pattern | Every Row On | On/Off Pattern indicates specific row patterns to be on or off. Select pre-defined planter All Row On pattern. For other pre-defined planter patterns or individual row settings, reference Operator’s Manual. |
| Pop/Block Pattern | Every Row Population | Determines which sensors are used to calculate population and those used only for blockage detection. Select pre-defined Every Row Population. For other pre-defined patterns, reference Operator’s manual. |

| TABLE B: Material Setup | Default Value/ Value to Enter | Controlled Hydraulic Drive Instructions/Definitions |
|---|---|---|
| Matrl Label | Matrl 1 | Material Name can be customized to accurately define the material’s type. Creating a name allows for quick identification at the Material Summary screen. |
| Type | Planter Control | Desired type of application control channel being used for a specific material. The Material Type must correctly match the Control Type to be able to select Material from the Material Summary screen and operate properly. |
| Units | Ks/Ac S/Sec | Automatically changes with the type of material application selected. Changes units for target application. |
| Preset Method | Enable | Enabled Preset Method allows 10 user-defined Target Rates to be adjusted from the Main Operate screen using Inc or Dec softkeys. A Disabled Preset Method increases/ decreases the Target Rate based on the % values set at the Material Configuration Setup screen. |
| Seeds per Rev | See Manual | Set to number of seeds per 1 disc revolution. |
| Disc Low Limit (Singulator Plus) | 5 | Set to desired min seed disc RPM. |
| Disc Low Limit (Precision Finger) | 40 | Set to desired min seed disc RPM |
| Disc High Limit (Singulator Plus) | 40 | Set to desired max seed disc RPM |
| Disc High Limit (Precision Finger) | 85 | Set to desired max seed disc RPM |
| High Pop Alarm | 15% | This is the percentage above the target population of the planter channel if rows are assigned to the planter channel. If rows are not assigned to a planter, this is the percentage above average planter population for all unassigned rows. |
| Low Pop Alarm | 15% | This is the percentage below the target population of the planter channel if rows are assigned to the planter channel. If rows are not assigned to a planter channel, this is the percentage below average planter population for all unassigned rows. |
| Product Level Alarm | | Sets the level to trigger an alarm alerting of low product levels. Entered value is an estimate in volume. |
| Row Fail Rate | 2/1 (2 seeds every 1 second) | Set to desired number of seeds per second to trigger seed sensor failure alarm. |

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### STEP 6: Planter Control Channel Setup

### (Controlled Hydraulic Drive)

1. At the Control Setup screen, press the Channel Setup button  .
2. Select Channel 1 and verify that the channel is set to Planter Control.
3. Enter desired values using **Table C** as reference.
4. After planter control setup, calibrate hydraulic valve by pressing the Valve Cal button  .
5. Ensure implement is raised. With brakes locked and transmission in PARK position, start engine.
6. Engage hydraulics and run engine at normal speed until hydraulic fluid is at operating temperature.
7. Verify point row clutches are turned ON.
8. **Do NOT perform this step unless meters are installed in all locations across planter row units or drive damage will occur.**
   Press the START button  . Turn the master switch to the ON position. The valve calibration will immediately start. Keep the hydraulics engaged until the calibration completes.
6. When the screen indicates calibration is complete, press the Channel Setup button  to return to Channel 1 home screen.
7. Turn the master switch OFF.
8. To set up additional control channels (planter or fertilizer control), press the Next Channel button  .
9. Press the Work Screen button  when channel configurations are complete to return to the Main Work screen.

Once a control channel has been established as Planter Control, any new materials established as Planter Control on the Material Setup screen will automatically be added as optional materials for Planter Control channels on the Control Setup screen.

### STEP 7: Row Monitor Setup

1. At the Main Work screen, press the Row Monitor button  .
2. Enter desired values using **Table D** as reference.
3. Press the Work Screen button  to return to the Main Work screen.

| TABLE C: Planter Control Setup | Default Value/ Value to Enter | Instructions/Definitions |
|---|---|---|
| Type | Planter Control | Set desired Channel Type as Planter Control. |
| Material Name | | Displays only materials that have been configured for the channel type. |
| Control Mode | AUTO | Auto is used in normal operating conditions calculating the rate of how the system is running. Manual mode acts as an override if application rate sensors are inoperable allowing the use of increase/decrease keys to set the flow rate for the control. Refer to System Configuration section of Operator’s manual for additional information. |
| Drive Type | PWM | A hydraulic valve varies the oil flow to the motor proportioned to the electric current supplied. |
| Drive Frequency | 100 Hz | If not using a DICKEY-john supplied valve, see the manufacturers specifications for drive frequency. |
| Input Filter | 50 | Feedback frequency filter for the control channel. DO NOT CHANGE. |
| Gear Ratio | 1.900 | Specifys the actual ratio from the feedback sensor to the seed meter shaft RPM. Number of revolutions the feedback sensor turns in relation to one revolution the seed meter turns. |
| Sensor Constant | 360 | Sensor Constant establishes the number of pulses for one revolution of the feedback sensor. If a DICKEY-john application rate sensor is used, the value should be set to 360.0. |
| # of Seed Rows | 47 | Entry of a specific number of seed rows for the control channel. Row assignment is given a priority based on the channel and will be assigned sequentially thereafter. Channel 1 is always assigned to the first set of rows, Channel 2 next set of rows, and so on. |
| Channel Width | 705 | Manual entry of the channel width for rows assigned to a specific channel. Width calculation can be determined by # of planter rows assigned to the channel multipled by the row spacing. |
| Precharge Time | +0.0 | Typically used during startup conditions in the field, a Precharge time is a specified length of time a control channel will operate at the defined precharge ground speed. Must be entered as a positive (+) number. |
| Delay Time | -0.0 | Length of time before the control channel will start after the master switch has been turned ON and the implement switch is in a lowered position. Must be entered as a negative (-) number. |

| TABLE D: Row Monitor Setup | Default Value or Value to Enter | Instructions/Definitions |
|---|---|---|
| Material Name | See Instructions | Material Name only appears on the Seed Monitor Setup screen when all Control Channels are disabled and material is set for Monitor only. This is only used for ground drive/nonhydraulic applications to monitor population with high and low alarms. A material must be configured and selected to activate alarms. |
| High Alarm Delay | 5 | Desired number of seconds that high population can be above high alarm point before alarm will sound. |
| Low Alarm Delay | 5 | Desired number of seconds that low population can be below low alarm point before alarm will sound. |
| Population Adjust | 100 | Enter a % to allow for seed sensor population inaccuracies to achieve the desired population display. 100% represents true calculation. |
| Population Filter | 50 | Set filter value to stabilize the monitored population display. Number can be set to 0% for no filtering and 99% for high level filtering. |
| Row Fail Rate | 2/1 (2 seeds every 1 second) | Set to desired number of seeds per second to trigger seed sensor failure alarm. |

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### STEP 8: Speed Set Calibration Setup

1. At the Main Work screen, press the Speed Set button .
2. Enter desired values using **Table E** as reference.
3. Press the Work Screen button when ground speed calibration configurations are complete to return to the Main Work screen.

### STEP 9: Accessory Sensor Setup

***Hopper Assignment***

1. At the Main Work screen, press the Next Page button .
2. Press the Module Configuration button to display the Module Configuration screen.
3. At the Module Configuration screen, press the Hopper Assign button .
4. Press Hopper Set button .
5. Enter desired values using **Table F** as reference.

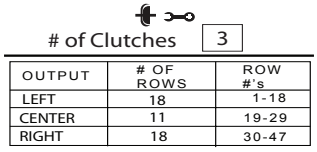
***RPM Assignment***

6. At the Module Configuration screen, press the Accessory Assignment button .
7. Press the RPM Setup button or NOTE: There must be at least 1 RPM sensor configured before the RPM Setup button appears on the screen.
8. Enter desired values using **Table F** as reference.

### STEP 10: Clutch Folding Module (CFM) Setup

The CFM is installed in the cab to control row clutches, marker, fold, fertilizer on/off, lift and hitch.

1. At the Main Work screen, press the Clutch CFG button to access the Clutch Configuration screen and verify that the correct # of clutches are configured for the system.
2. The Clutch CFG button only appears as a top level button when a planter output module and clutch folding module are installed.




| TABLE E: Speed Set | Default Value or Value to Enter | Instructions/Definitions |
|---|---|---|
| Source | Digital Frequency | Select CAN Ground if radar is connected to ISO tractor cab harness. Select Digital Frequency if radar or hall-effect is connected to WSMT actuator harness. |
| Gspd Constant | 12192 | Input based on pulse count produced by the ground speed sensor over 400’ distance. See Operator’s manual for calibration instructions. |
| Shutoff Speed | 0.5 mph | Set desired minimum ground speed allowed before the system shuts off. |
| Minimum Override | 2.0 mph | Set to operate when actual ground speed falls below the designated value. Control will operate at this speed until actual ground speed rises above minimum override speed or actual speed drops below shutoff. |
| Master Sw Timeout | 10 | Set to desired number of seconds system shuts off if the master switch is turned on and there is no ground speed. Toggle master switch to restart the system and turn off alarm. |
| Gspd Fail Alarm Delay | 5 | Set to desired number of seconds alarm sounds after the ground speed is zero and seed flow continues. (Monitor only) |
| Precharge Ground Speed | 0 | Set to the desired speed the system will use when a precharge time has been enabled for a control channel. Refer to Table C1: Planter Control Setup for Precharge Time. This setting will only display when a Precharge Time has been entered. |
| Implement Lift | Enabled | Implement lift switch, when enabled, displays an implement lift indicator on the Main Operate screen indicating implement lift position as up or down. Control channels can be turned on and off without using the master switch. |

| TABLE F: Accessory Setup | Default Value or Value to Enter | Instructions/Definitions |
|---|---|---|
| **Hopper Setup** | | |
| # of Hoppers | 2 (base unit)<br>2 more (optional) | # of hopper sensors connected to each module (4 sensors maximum). # of hopper data items for each listed module and the Hopp #’s value will automatically populate if Auto Config is used to configure installed sensors. |
| Logic Level | Active Lo | Sets the active state to low signifying that an alarm is generated if the sensor’s output is in a low state. Use this setting if the connected sensor outputs a low condition when empty similar to the DICKEY-john hopper sensor. |
| Alarm Delay | 5 sec | Controls the delay time between the detection of a high/low hopper alarm condition and the generation of the resulting alarm. The value is entered in seconds. |
| Channel | | Assigns hopper sensor to channel. |
| **RPM Setup** | | |
| High Alarm (fan speed) | 4200 rpm | Sets the RPM value at which a high RPM warning error is generated. |
| Low Alarm (fan speed) | 2900 rpm | Sets the RPM value at which a low RPM warning error is generated. |
| High Alarm Delay | 10 sec | Establishes the delay between the detection of a high RPM alarm condition and the resulting alarm display. The value is entered in seconds. |
| Low Alarm Delay | 10 sec | Establishes the delay between the detection of a low RPM alarm condition and the resulting alarm display. The value is entered in seconds. |
| RPM Constant | 3 pulses/rev | Number of pulses per sensor revolution. |
| RPM Filter | 0 | Filters the signal out of the RPM sensor. |
| Disable Control on Low Alarm | Disabled | Allows for disabling of all Control Channels if the RPM value of the selected sensor falls below the low alarm level setting. |

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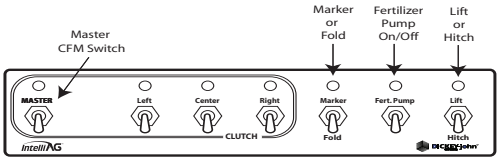
### STEP 11: Clutch Folding Module Operation

1. The Planter Section controls turns the left, center, and right clutch controls on and off.
2. The master switch must be in the ON position to activate any planter section. When a clutch control is ON, a green light will illuminate.
3. Marker/Fold Switch should be in the UP (Marker) position during planting. In the DOWN (Fold) position, the switch controls the fold of the main frame.
4. The Fertilizer Pump switch is turned ON when in the UP position. Press the switch in the DOWN position to turn OFF.
5. Lift/Hitch switch should be in the UP (Lift) position during normal operation. In the hitch position, the switch should be in the DOWN (Hitch) position to unlock and extend the telescoping tongue in preparation of folding the implement for transport.
6. Lift/Hitch switch MUST be in the hitch position and hydraulic circuit in FLOAT when transporting planter equipped with hydraulic-operated tongue hitch. NOTE: Lift/Hitch switch has no function if planter has standard 3-point hitch operated tongue hitch.



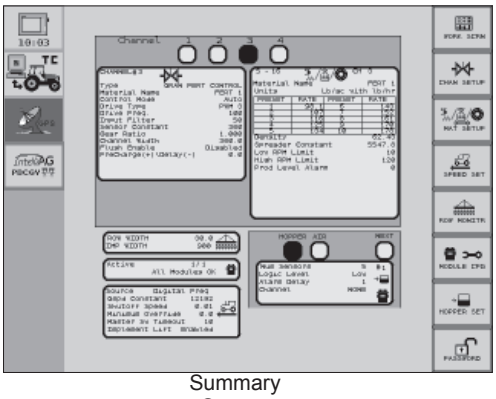

### STEP 12: 5 Revolution Test

1. Press the Control Setup button  .
2. Press the Channel Setup button  .
3. Press the Next Page button  .
4. Ensure implement is raised before starting 5 Rev Test.
5. With brakes locked and transmission in PARK position, start tractor engine.
6. Engage hydraulics and run engine at normal speed until hydraulic fluid is at operating temperature.
7. Press the 5 Rev button  .
8. Test Ground Speed and Row data must be entered to perform test.
9. Press and hold remote test button to initiate 5 Rev Test.

### STEP 13: Summary Screen

The Summary screen provides an overview of setup constants for active control channels.

1. At the Main Work screen, press the Next Page button  .
2. Press the Summary button  .
3. To view specific control channel configurations, press the respective control channel box 1-4.
4. Press inside a yellow highlighted box to open a specific screen for editing.
5. Press the Work Screen button  to return to the Main Work screen.



Summary Screen

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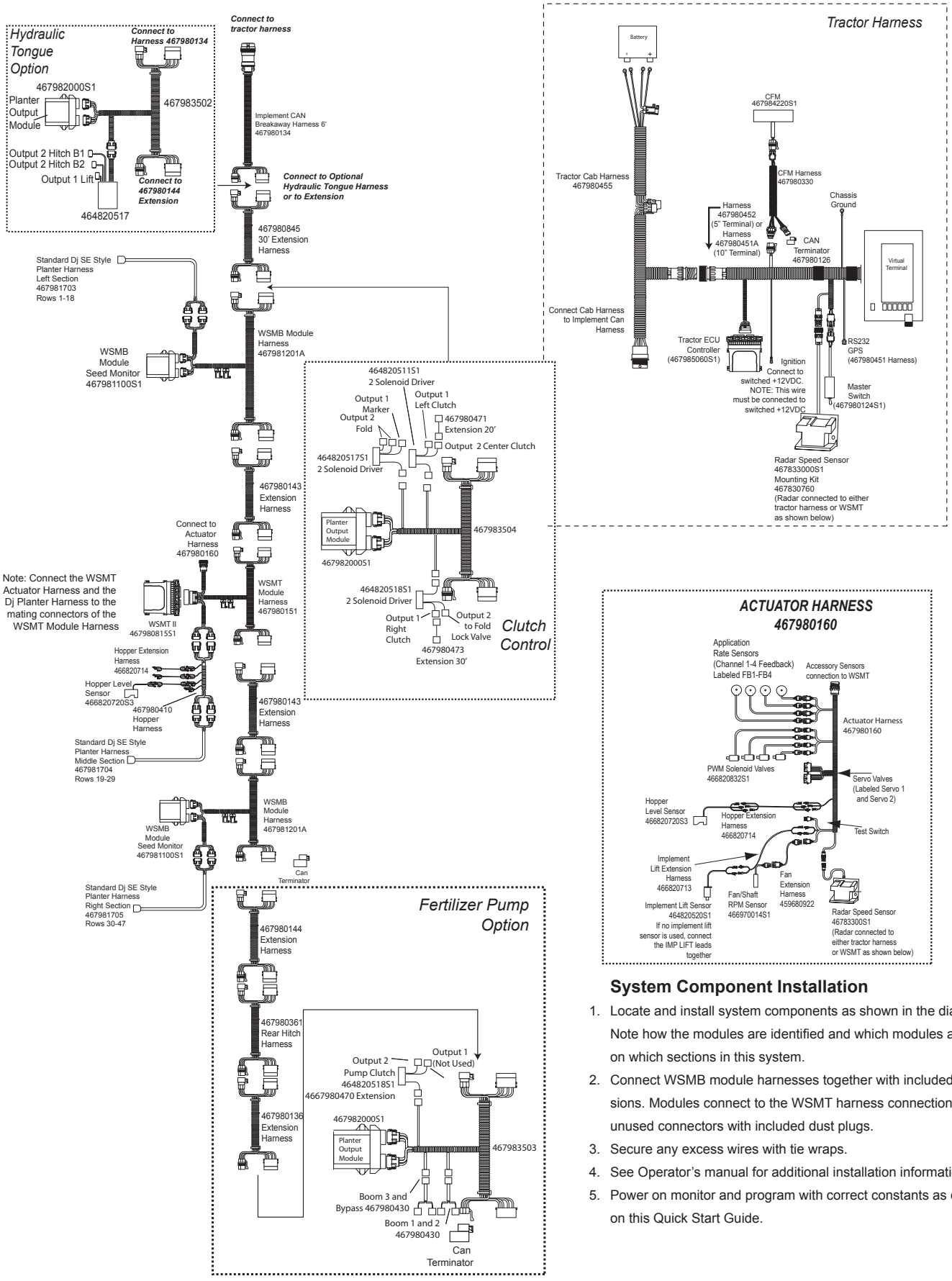


## System Component Installation

1. Locate and install system components as shown in the diagram. Note how the modules are identified and which modules are located on which sections in this system.
2. Connect WSMB module harnesses together with included extensions. Modules connect to the WSMT harness connection. Plug all unused connectors with included dust plugs.
3. Secure any excess wires with tie wraps.
4. See Operator’s manual for additional installation information.
5. Power on monitor and program with correct constants as described on this Quick Start Guide.

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